

Generalizing and Scaling Optimal Transport

Généralisation et Passage à L'Échelle du Transport Optimal

2025-05-11

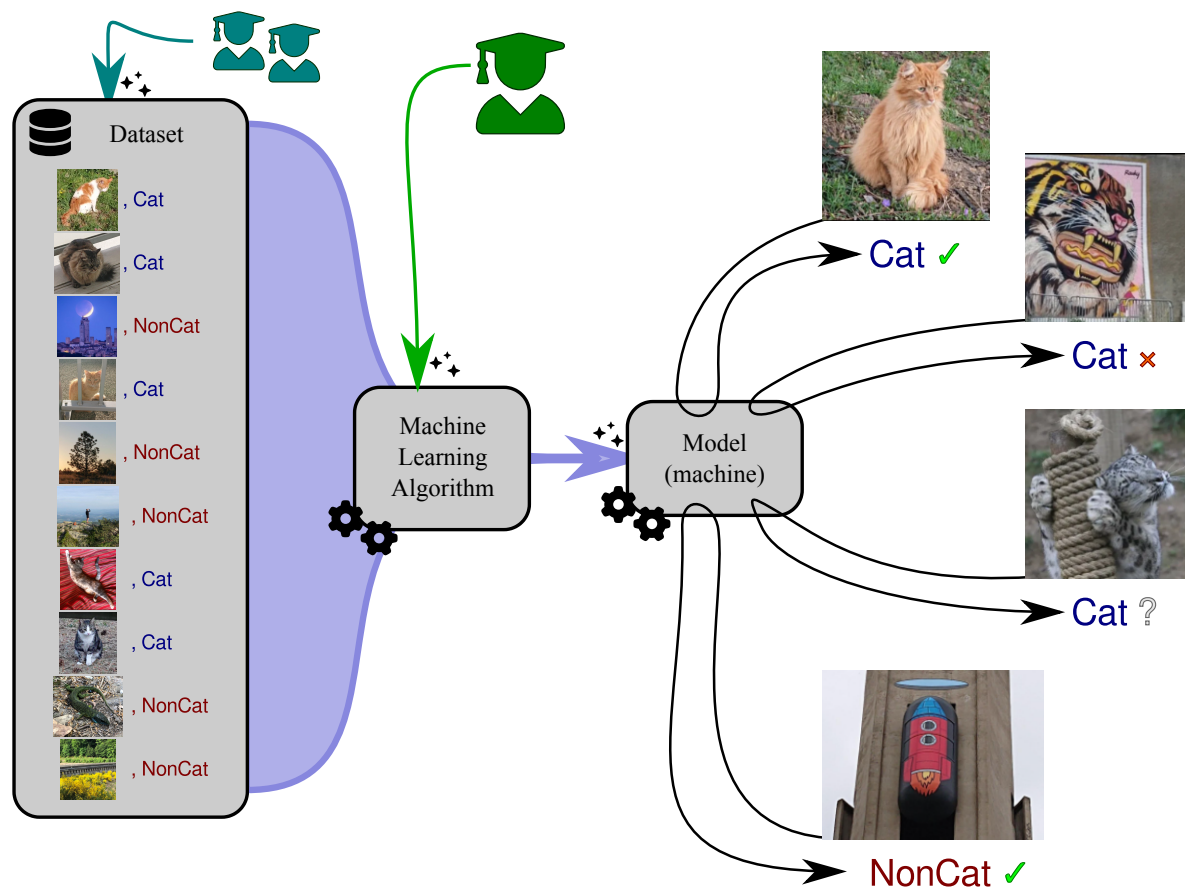
Rémi Emonet

Célébration des 10 ans de la FIL

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Introduction

What is Machine Learning?

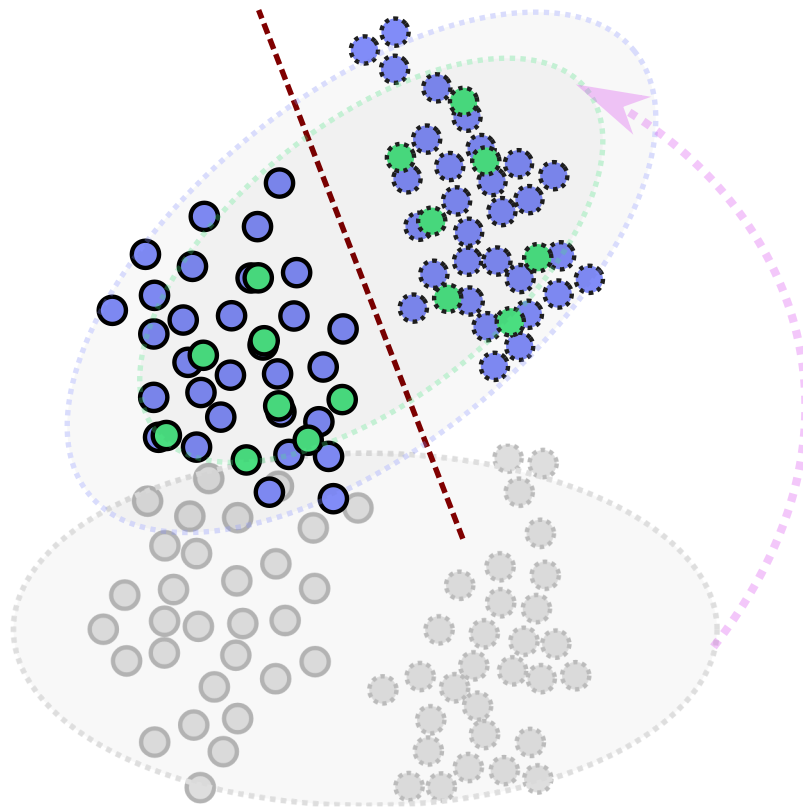


- theoretical foundations
- algorithms
- certificates
- many facets
 - imbalance
 - fairness
 - privacy
 - explainability
- ...

Transfer Learning and Domain Adaptation

Target domain
(labels?)

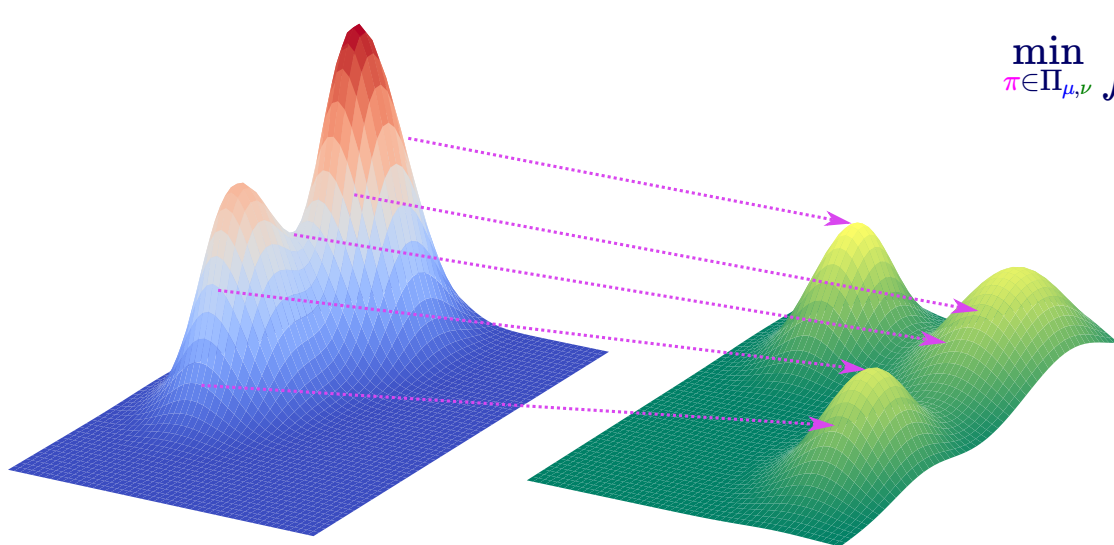
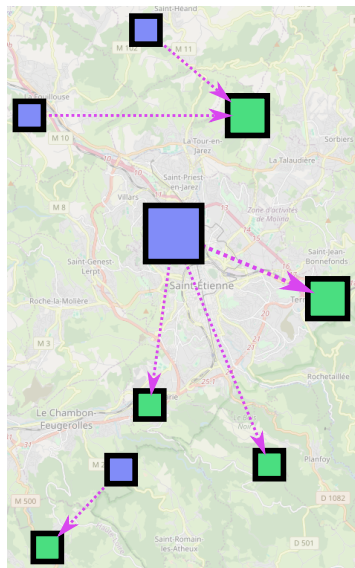
Source domain
(labelled)



Distribution/dataset
alignment

- key for domain adaptation
- need a notion of distance

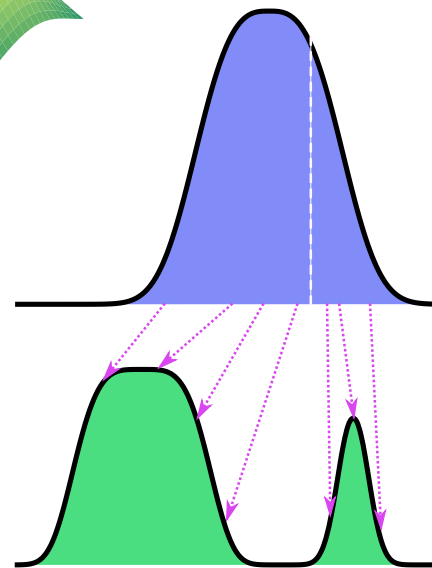
Optimal Transport: distance between distributions (discrete, continuous)



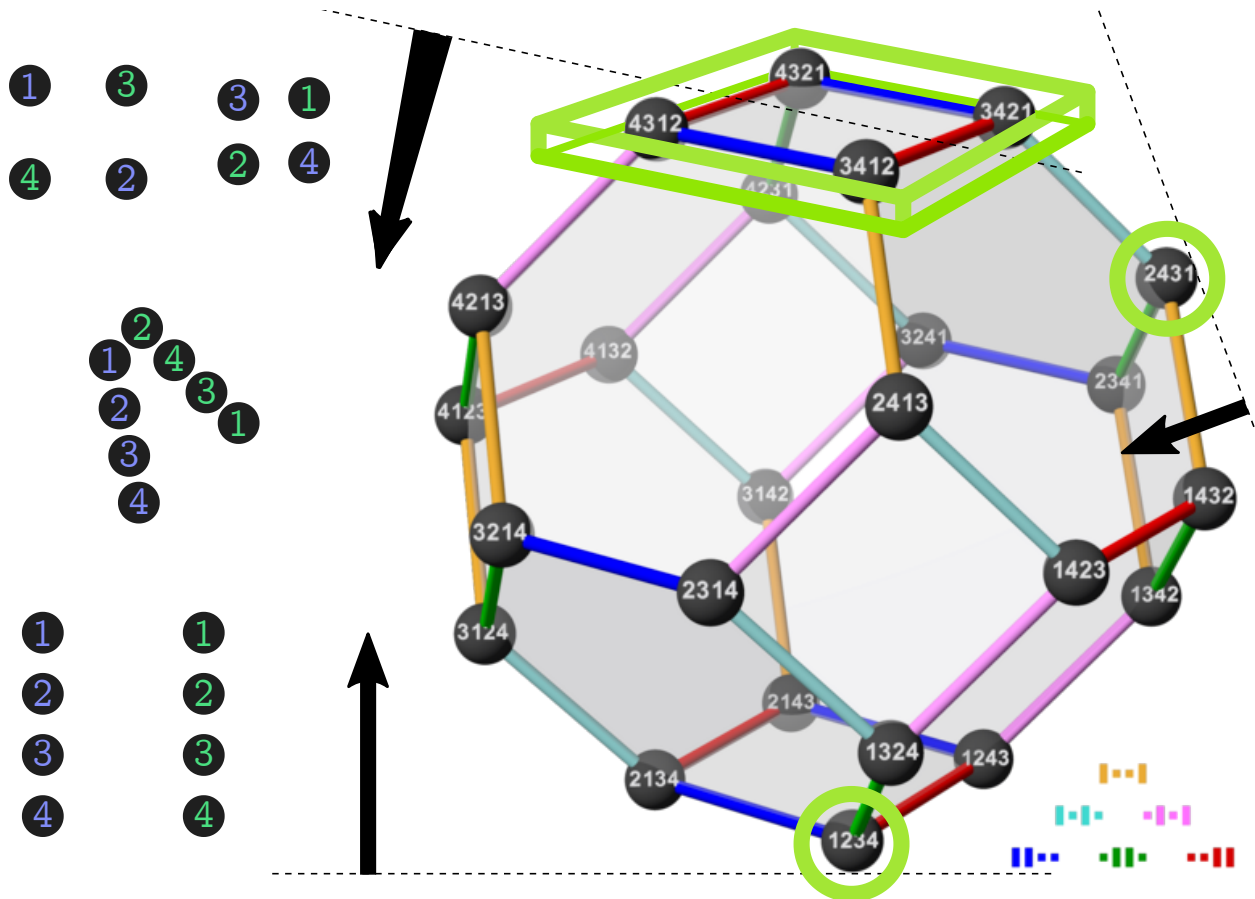
$$\min_{\pi \in \Pi_{\mu, \nu}} \int_{\mathcal{X} \times \mathcal{Y}} c(x, y) d\pi(x, y)$$

$$\min_{T \in \Pi_{a, b}} \sum_{i, j} T_{ij} C_{ij}$$

$$\min_{T \in \Pi_{a, b}} \langle T, C \rangle$$



Birkhoff Polytope, Permutohedron and Computation Complexity



- OT Problem
 - Linear problem
 - Linear constraints
 - Birkhoff polytope
- Complexity
 - $O(n^3)$ (general case)
 - $O(n \log(n))$ in 1D

Overview

- Introduction
- Generalized Optimal Transport as a Modelling Tool
- Scaling Optimal Transport
- Generative Models and Optimal Transport
- Deriving Generalization Guarantees

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Generalized Optimal Transport as a Modelling Tool

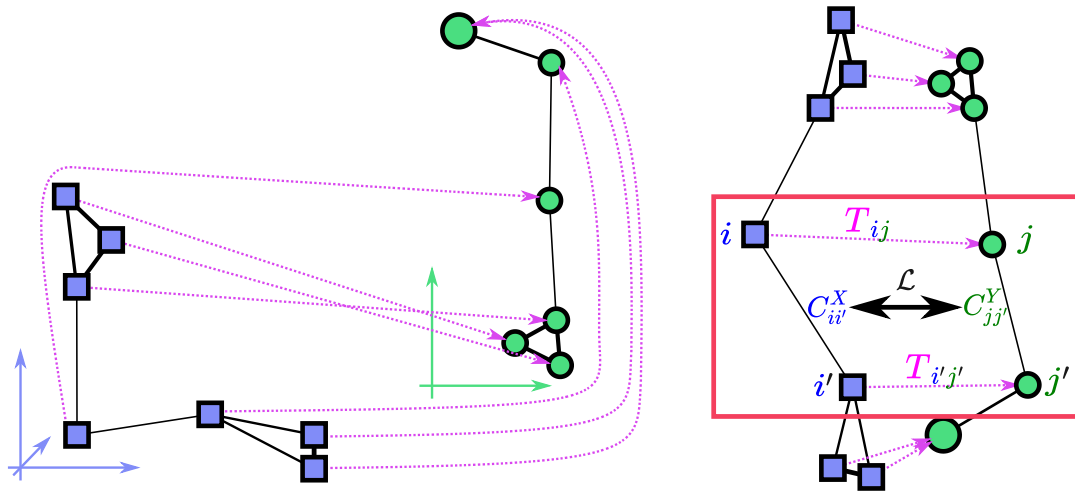
Transport Between Heterogeneous Domains: Gromov-Wasserstein

Reminder, optimal transport problem $OT(C) = \min_{T \in \Pi_{a,b}} \sum_{i,j} T_{ij} C_{ij} = \min_{T \in \Pi_{a,b}} \langle T, C \rangle$

⇒ **limited to data in the same space** (to define C)

Gromov-Wasserstein problem $GW(C^X, C^Y) = \min_{T \in \Pi_{a,b}} \sum_{i,j} \sum_{i',j'} T_{ij} T_{i'j'} \mathcal{L}(C_{ii'}^X, C_{jj'}^Y)$

- matches source points to target points
- minimize the difference of distances
 - between a pair of source points
 - and a pair of target points
 - that are mapped onto each other
- ⇒ graph matching



Fused Gromov Wasserstein « $FGW(C, C^X, C^Y) = (1 - \beta) \cdot OT(C) + \beta \cdot GW(C^X, C^Y)$ »

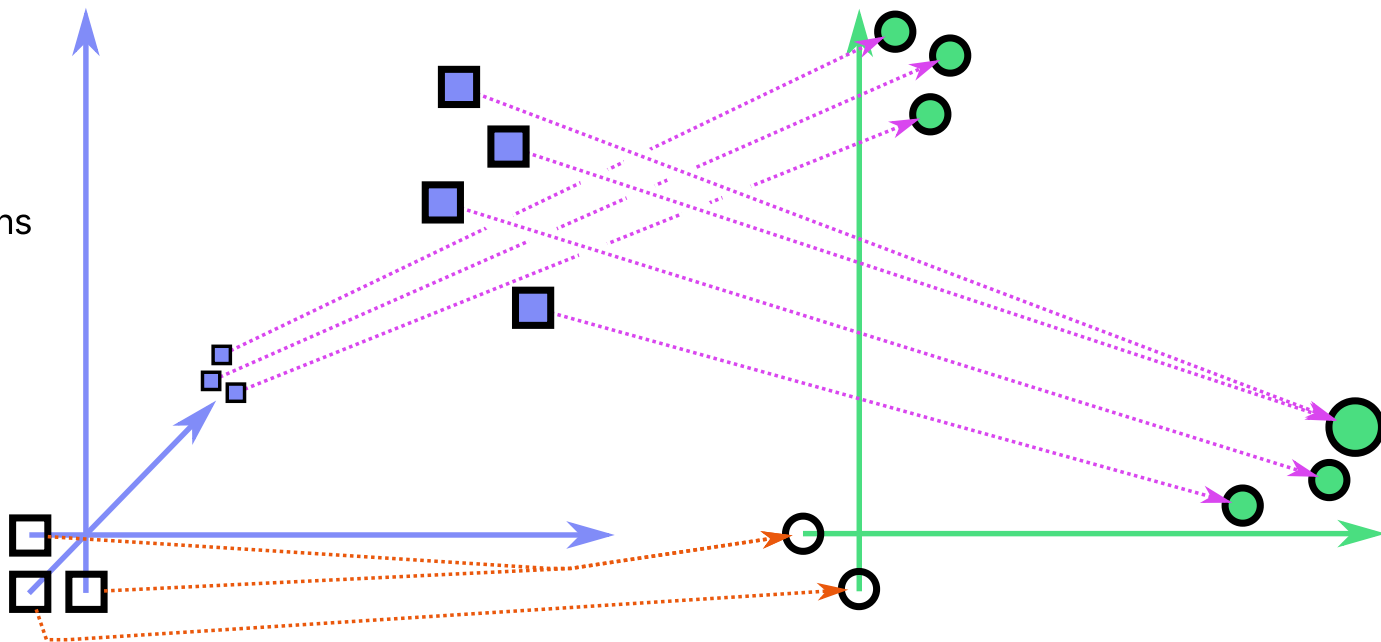
Optimal Transport Between Heterogeneous Domains: Co-OT

Co-Optimal Transport problem

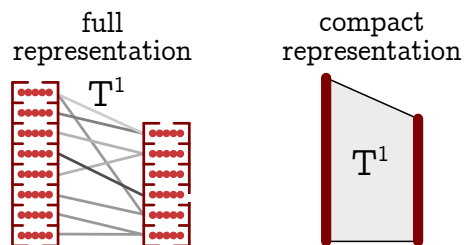
$$Co-OT(X, Y) = \min_{T^1 \in \Pi_{a^1, b^1}} \min_{T^2 \in \Pi_{a^2, b^2}} \sum_{i^1, j^1} \sum_{i^2, j^2} T^1_{i^1 j^1} T^2_{i^2 j^2} \mathcal{L}(X_{i^1 i^2}, Y_{j^1 j^2})$$

Matches

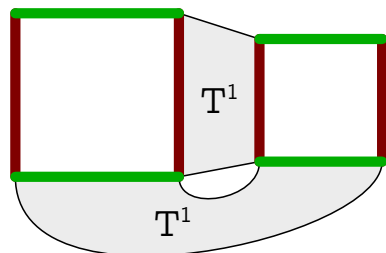
- source/target points
- sources/target dimensions
- with 2 transport plans



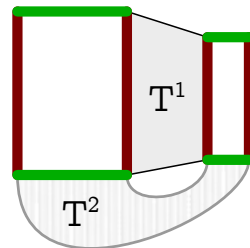
Generalization: OTT* (*Optimal Tensor Transport*)



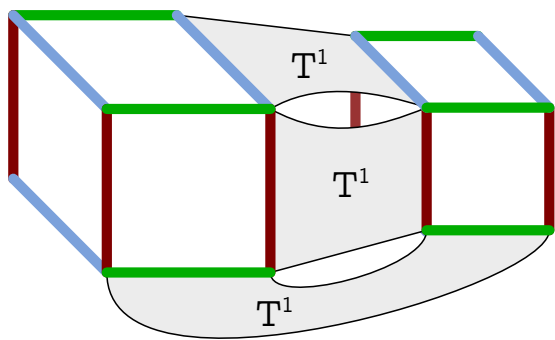
a) OTT₁ (OT) (Fs = Ft = 5 features)



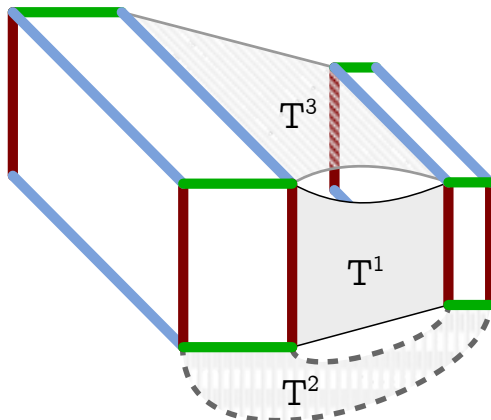
b) OTT₁₁ (GW)



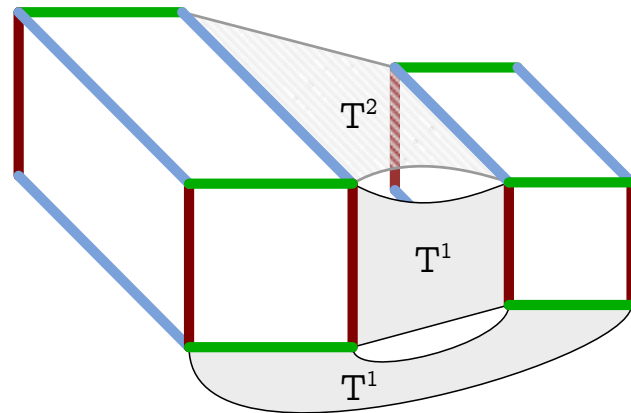
c) OTT₁₂ (Co-OT)



d) OTT₁₁₁ (triplets)



e) OTT₁₂₃ (triCo-OT)



f) OTT₁₁₂ (GW collections)

More axes of generalization

- Mixed problems ("fused")
- Partial transport, relaxed constraints
- Multi-marginal
- Class information handling (for domain adaptation)
- Representation/metric learning
- Time-series constraints

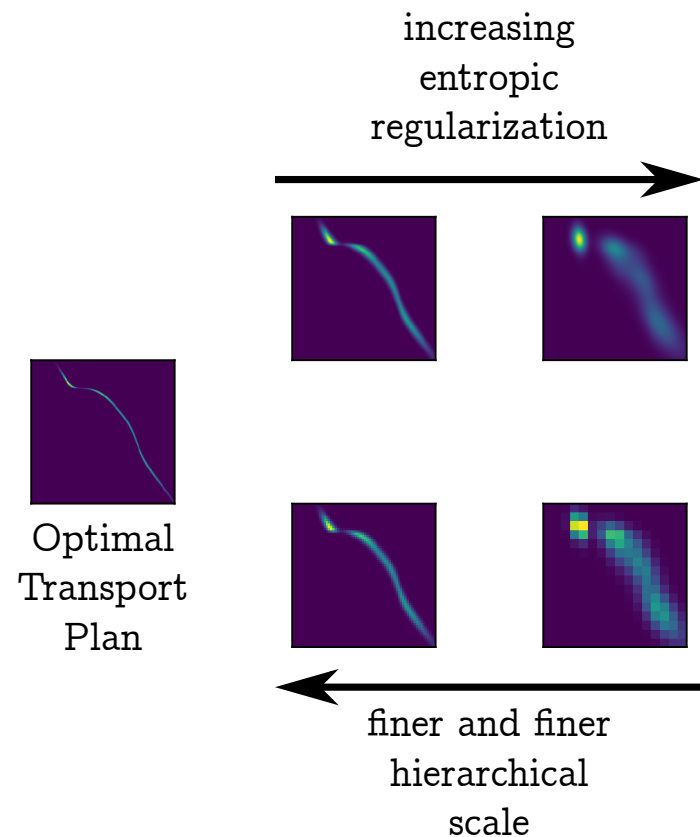
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Scaling Optimal Transport

Main Means for Scaling Optimal Transport (and Generalized OT)

- Entropic regularization
- Hierarchical (for spatial or groupeable data)
- Sliced approaches / random projections
- Stochastic approximations

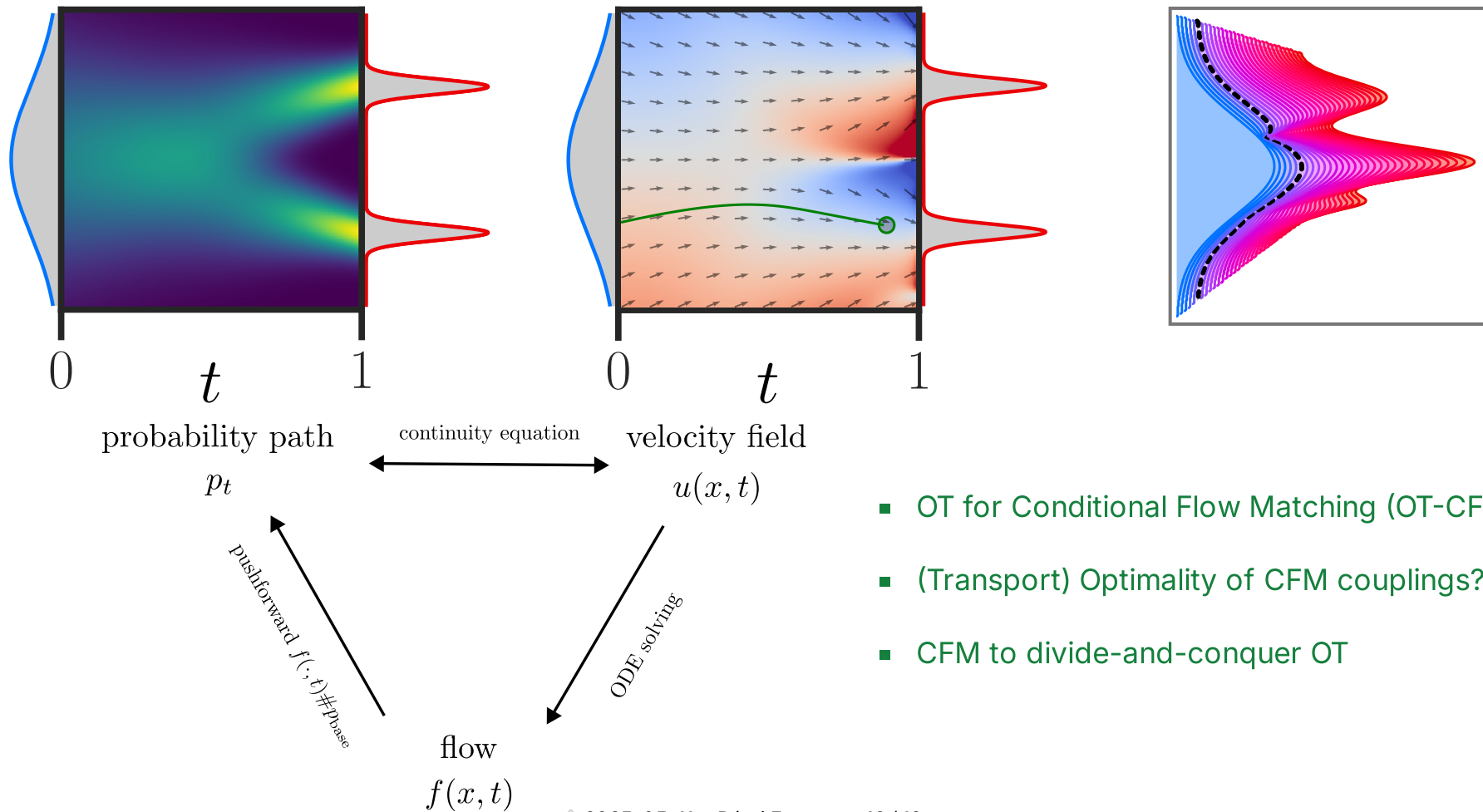


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Generative Models and Optimal Transport

Conditional Flow Matching / Diffusion / Optimal Transport



- OT for Conditional Flow Matching (OT-CFM)
- (Transport) Optimality of CFM couplings?
- CFM to divide-and-conquer OT

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Deriving Generalization Guarantees

- Probabilistic view of (generalized) optimal transport
- **what:** e.g., sample complexity, convergence, generalization bounds
- **how:** e.g., the PAC-Bayesian framework

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Conclusion

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Thank You! Questions?

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Supplementary slides

SaGroW : Algorithme d'optimisation pour GW et OTT

Rappel, problème de Gromov-Wasserstein (ré-écrit)

$$GW(\mathcal{C}^X, \mathcal{C}^Y) = \min_{T \in \Pi_{a,b}} \sum_i \sum_j T_{ij} \sum_{i',j'} T_{i'j'} \mathcal{L}(\mathcal{C}_{ii'}^X, \mathcal{C}_{jj'}^Y)$$

Algorithm SaGroW

Require: $\mathbf{a}, \mathbf{b}$ (probability vectors of μ and ν), $\mathcal{C}^X, \mathcal{C}^Y$ (cost matrices), $\mathcal{L}$ (loss function), M (number of samples), ϵ (entropy regularization), α (partial update weight)

- 1: $T_0 = \mathbf{a}\mathbf{b}^\top$
 - 2: **for** $s = 0$ **to** $S-1$ **do**
 - 3: $(j_m, l_m) \sim \text{Sample}(T_s) \ \forall m \in \llbracket 1, M \rrbracket$
 - 4: $\hat{\Lambda}_{ik} = \frac{1}{M} \sum_{m=1}^M \mathcal{L}(\mathcal{C}_{i,j_m}^X, \mathcal{C}_{k,l_m}^Y) \ \forall i, k \in \llbracket 1, N \rrbracket$
 - 5: $T'_s = \text{solve the regularized OT problem } (\mathbf{a}, \mathbf{b}, \hat{\Lambda}, \epsilon)$
 - 6: $T_{s+1} = (1 - \alpha)T_s + \alpha T'_s$
 - 7: **end for**
 - 8: **return** T_{S-1}
-

- termes vues comme des espérances mathématiques
- algorithme stochastique par échantillonnage
- complexité contrôlée et possibilité de transport 1d